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		Substitute for form 1449A/	PTO	Application Number	10/597,756		
		RMATION DISC		Filing Date	August 8, 2007		
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				Examiner Name	Not Yet Assigned		
Sheet	heet 1 of 3		Attorney Docket Number	34621			
			U.S. PATENT	DOCUMENTS			
Examiner Initials*	Cite No. ¹	Document Number	Publication Date DD-MMM-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear		
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⁴ For Japanese patent documents, the indication of the year of the reign of the Emperor must precede the serial number of the patent document.

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Substitute for form 1449A/PTO						Application Number 10/59		7,756		
INFORMATION DISCLOSURE								August 8, 2007		
STATEMENT BY APPLICANT						Filing Date First Named Inventor				
								Omer EINAV		
(use as many sheets as necessary)					Art Unit Examiner Name		3764	3764 Not Yet Assigned		
							Not Y			
Sheet		2 Of	3	3 A		Docket Number	34621			
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Complete if Known Substitute for form 1449A/PTO Application Number 10/597,756 INFORMATION DISCLOSURE Filing Date August 8, 2007 STATEMENT BY APPLICANT First Named Inventor Omer EINAV Group Art Unit 3764 (use as many sheets as necessary) **Examiner Name** Not Yet Assigned Attorney Docket Number 34621 Sheet Of OTHER PRIOR ART – NON PATENT LITERATURE DOCUMENTS Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the Examiner Cite item (book, magazine, journal, serial symposium, catalog, etc.) date, page(s), volume-issue number(s), T^2 Initials No. publisher, city and/or country where published. 54 Backlife "The Backlife Idea", Product Information, http://www.backlife.com, 27 55 Bak "The Complex Motion of Standing Still. Hydraulics, Sensors, and Human Modeling Dsta-Unified by Proprietary Software", http://www.designnews.com/article/CA73202, 5 P., 2001. Burgar et al. "Development of Robots for Rehabilitation Therapy: The Palo Alto 56 VA/Stanford Experience", Journal of Rehabilitation Research and Development, 37(6): 663-673, 2000. Cameron et al. "Micromodular Implants to Provide Electrical Stimulation of 57 Paralyzed Muscles and Limbs", IEEE Transactions on Biomedical Engineering, 44(9): 781-790, 1997. Abstract. Graupe "EMG Pattern Analysis for Patient-Responsive Control of FES in 58 Paraplegics for Walker-Supported Walking", IEEE Transactions on Biomedical Engineering, 36(7): 711-719, 1989. P.711, I-h Col., Paragraph 1 -r-h Col., Paragraph 1, Figs. 3, 5, P.716, 1-h Col., Figs. Messinger "ReAbility Games: Island Hunt Catch'em Patrol Muzment", Detailed 59 Specifications Document, NOKs Technologies, Version 1.0, 16 P., 2004. Micromedical "BalanceQuest: Computerized Dynamic Posturography", 60 Micromedical Technologies, http://www.micromedial.com, 6 P., 2001. 61 Motek "Motek Medical Rehabilitation: Rehabilitation", http://www.e- motek.com>, 1 P. Peasgood et al. "EMG-Controlled Dosed Loop Electrical Stimulation Using A 62 Digital Signal Processor", Electronics Letters, 36(22): 1832-1833, 2000. P.1832, lh Col., Paragraph 1, Fig.1, P.1833, r-h Col., Paragraph 1. Richardson et al. "Comparing Smooth Arm Movement With the Two-Thirds Power 63 Law and the Related Segmented-Control Hypothesis", The Journal of Neuroscience, 22(18): 8201-8211, 2002. Viviani et al. "Minimum-Jerk, Two-Thirds Power Law, and Isochrony: Converging 64 Approaches to Movement Planning", Journal of Experimental Psychology: Human Perception and Performence, 17: 32-53, 1995. Abstract. Viviani et al. "Trajectory Determines Movement Dynamics", The Journal of 65 Neuroscience, 7: 431-437, 1982. Examiner Date Considered Signature

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